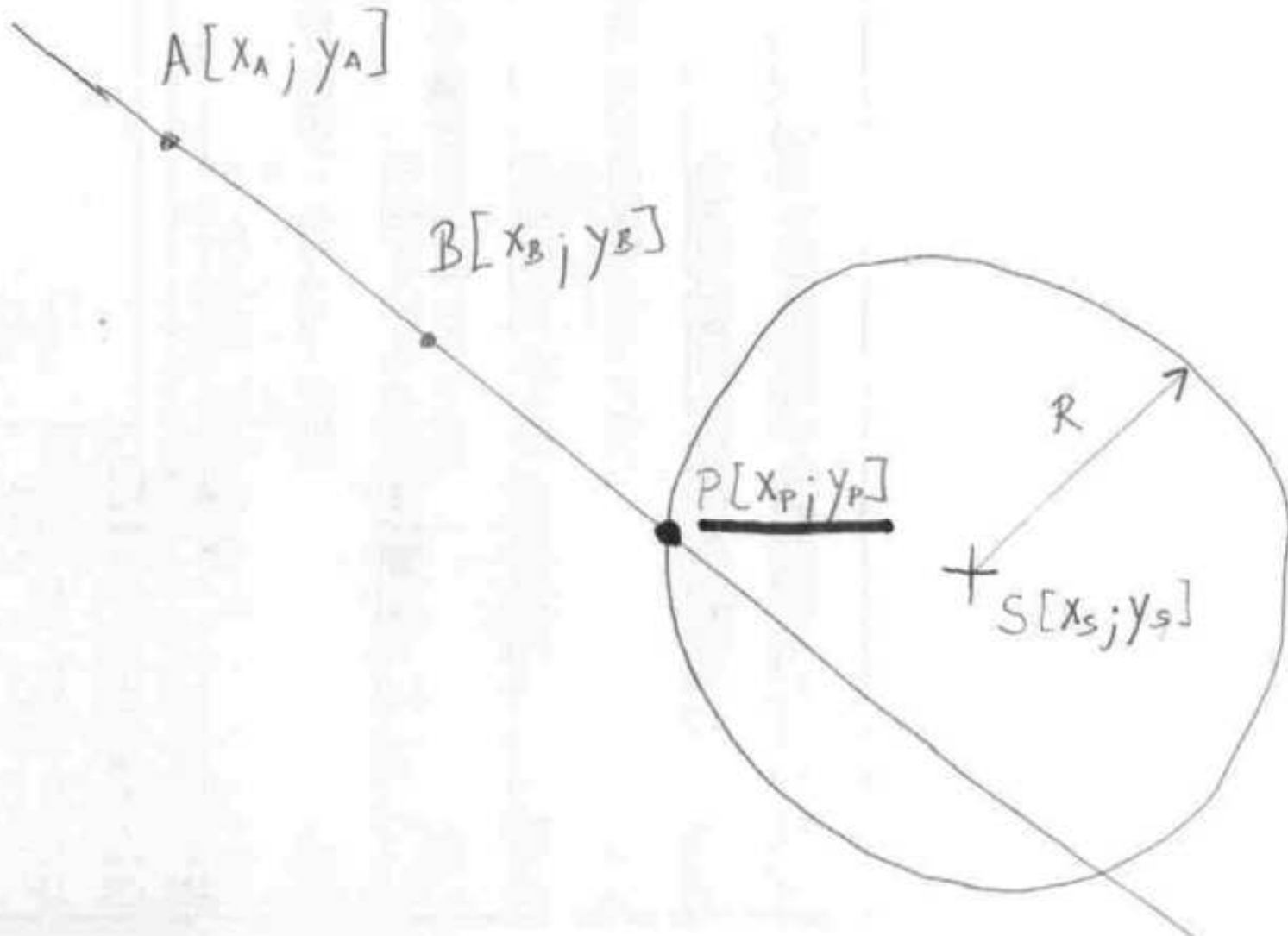
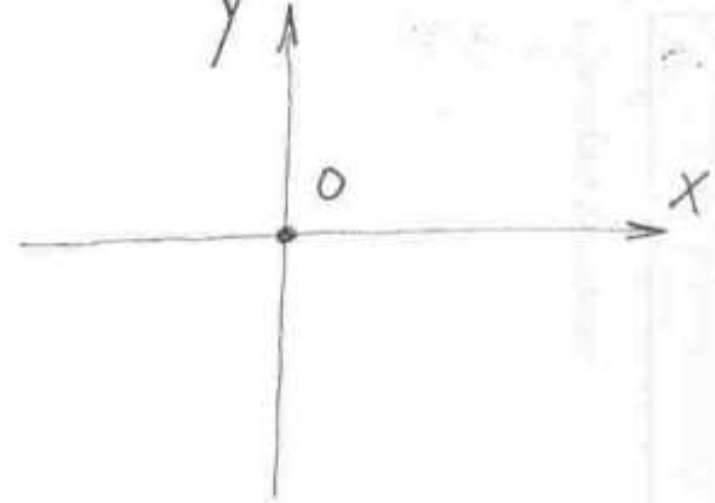


ZNAM: $x_A; y_A$
 $x_B; y_B$
 $x_S; y_S$
 R



HLEDÁM:
 $x_P; y_P$